Effects of 3D Magnetic Field Structure to MHD Equilibrium and Stability

- aspects from Stellarator/Heliotron Researches

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Outline

- 1. What is Stellarator?
- 2. The Large Helical Device LHD -
- 3. MHD Equilibrium in 3D Field
- 4. Interaction of the instability and 3D Field
- 5. Application of 3D tools to Tokamak
- 6. Summary

1. What is Stellarator?

Another candidate for Fusion Reactor

Why is the rotational transform necessary?

For simple torus...

Charge separation appears by grad-*B* drift.



Electric field is driven.



Disruption!

To cancel the charge separation, the connection between up and down of the plasma is necessary. => twist the field lines.



http://www.scidacreview.org/0801/html/fusion1.html

Classification of the rotational transform creating

C.Mercier, "Lectures in Plasma Physics"

- •Toroidal current along the axis => tokamaks
- •Torsion of the axis => 8-figure stellarator
- Modulation of flux surfaces



L.Spizter Jr.



Model A stellarator, 1951, Princeton

Classification of the rotational transform creating

C.Mercier, "Lectures in Plasma Physics"

- Toroidal current along the axis
- Torsion of the axis
- Modulation of flux surfaces

Stellarators create the rotational transform by 3D shaping.



Advantages:

- 1. Steady-state operation without current drive
- 2. No disruptin

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Stellarators create the rotational transform by 3D shaping.



Disadvantages:

- **1. Engineering problems**
- 2. Degradation of the confinement by helical ripples

Model C Stellarator "Race Track"



Courtesy to PPPL

Helical-axis Stellarator "Asperator"



Fig. 1. Asperator NP-4.



Y.Funato, *et al.*, Japanese Journal of Applied Physics **22** (1983) 1188 Y.Funato, *et al.*, Japanese Journal of Applied Physics **27** (1988) 821

LHD has worked very well for 10 years Courtesy to H.Yamada SOFT2008

- ✓ Construction completed within the eight-year plan (FY1990-1997)
- $\checkmark\,$ Operation for 10 years
- engineering base of a large-scale superconducting and cryogenic system for a fusion reactor

< LHD basic dimension >

- Outer diameter 13.5 m
- Cold mass
 820 ton
- Total weight 1500 ton
- Magnetic field 3 T
- Magnetic energy 0.77 GJ

Several-month-long operation, 11 times since 1998

- Operational time of He
- compressor : 51,654 hours
 - → Duty = 99.3 %
- Coil excitation number : 1,168 times
- Plasma discharges
 - : 84,869 shots



Stellarators have "vacuum flux surfaces"



Vacuum flux surfaces in a heliotron configuration

Stellarator field has toroidal periodicity.

Flux surfaces are changed due to the "plasma response"



However, the plasma response strongly depend on the vacuum configuration!

Stellarator is not disruptive



Collapsed events are observed but not disruptive!



Plasma recovered after events!

What is the contribution from the stellarator research to ITER?

In tokamaks, the magnetic field to confine the plasma is produced by the plasma itself!

 $B_{\text{total}} = B_{\text{tor,vac}} + B_{\text{pol,plasma}} + B_{\text{response}}$

In stellarators, the magnetic field to confine the plasma is produced by external coils for the vacuum.

$$B_{\text{total}} = B_{\text{tor,vac}} + B_{\text{pol,vac}} + B_{\text{response}}$$
$$B_{\text{response}} = B_{\text{total}} - B_{\text{tor,vac}} - B_{\text{pol,vac}}$$

Stellarators are platforms to explorer 3D physics!

2. The Large Helical Device (LHD)

Present View! Large Helical Device (LHD)

External diameter13.5 mPlasma major radius3.9 mPlasma minor radius0.6 mPlasma volume30 m³Magnetic field3 TTotal weight1,500 t

ATT P

ECR 84 – 168 GHz World largest superconducting coil systemMagnetic energy1 GJCryogenic mass (-269 degree C)850 tTolerance< 2mm</td>

Local Island Divertor (LID)

ICRF 25-100 MHz

NBL





LH	ID
R	= 3.9 m
a	= 0.6 m
В	= 3 T
Pheat	= 20 MW

Superconducting coils with magnetic energy of 0.9GJ

80sec Discharge

LHD has large flexibility of magnetic configuration





Typical lota profile and well/Hill boundary



In LHD, pressure gradient driven modes are important; stability depends on magnetic well depth.

- With increase of beta, the well region expands.
- Unstable region [.][⊆] remains in the edge region.
- Resistive interchange mode always observed in the edge. (slightly increase transports)



Magnetic well is created due to the Shafranov shift





Subjects of MHD studies in Heliotron



MHD equilibrium, **stability** and **transport** are key issues for production of high-beta plasmas:

MHD Equilibrium:

- Change of magnetic topology and relationship with beta-limit
 - Stochastization of peripheral magnetic field lines

MHD Stability:

- Effect of pressure-driven mode (Interchange and Ballooning modes)
- Magnetic hill in the periphery

Transport:

- transport related with finite-b effects (magnetic topology, beta and so on)
- Particle loss due to an increment of helical ripple, turbulence caused by steep ∇p



3.3D MHD Equilibrium studies

3.1 Stochastization due to plasma response

High-beta Steady State Discharge



► <
$$\beta$$
>_{max} ~ 4.8 %, β_0 ~ 9.6 %, H_{ISS95} ~ 1.1

- ▶ Plasma was maintained for $85\tau_E$
- Shafranov shift $\Delta/a_{eff} \approx 0.25$
- Peripheral MHD modes are dominantly observed.







High-beta Discharge – Pellet Injection –

Perpendicular-NBI was applied after several pellets were injected and tangential NBI is turned off which leads to reduction of Shafranov shift.

MHD activity is not enhanced in highbeta regime with more than 4 %





Achievement of the High beta plasma in LHD





Sustainment of the high-beta plasma is not a serious problem in helical system($\tau_{duration}/\tau_{E} > 100$). Limited only by the heating source.

Question: How far is from the beta limit?

How about is the magnetic surface topology?



In the peripheral region, magnetic field lines become stochastic as b increases. The volume inside LCFS shrinks drastically.



Control Coil Variation Changes Flux Surface Topology



- Calculation: at ~ fixed β, I_{CC}/I_M=0.15 gives better flux surfaces
- At experimental maximum b values -- 1.8% for $I_{CC}/I_{M} = 0$
 - -- 2.7% for $I_{CC}/I_{M} = 0.15$

calculate similar flux surface degradation

Courtesy to M.C.Zarnstorff and A.H. Reiman

Edge T_e does not respond to P_{ini}



- Edge T_e and ∇T_e does not change with increasing P_{inj} !! \Rightarrow Radial transport degrading as power increases
- Fixed density, and constant n_e profile. Increase in β due to core T_e increase
- Edge ∇T_e lower for $\iota = 0.575 \implies$ higher radial transport.

Courtesy to M.C.Zarnstorff and A.H. Reiman

Results from HINT well describes deformation of magnetic surfaces



Significant pressure ($T_{\rm e}$) gradient exists in the edge stochastic area

Hypothesis

- 1) Plasma heals flux surfaces
- 2) Profile is consistent with characteristics of stochastic field
- 3) Somewhere between 1) & 2)
 - L_{C-TB} : connection length between the torus-top and - bottom
- ✓ L_c >> L_{c-тв}
 - ➔ Pfirsch-Schlüter current is effective
 - ➔ Secure MHD equilibrium
- ✓ L_c >> MFP (even under a reactor condition)
 - ➔ Plasma is collisional enough to secure isotropic pressure

2010/6/4





How large is the stochasticity?





Degradation of surface quality due to β



•Two arrows indicate the position of well-defined LCFS on the equatorial plane.

•Flux surfaces in the peripheral region degrade due to the increased β.

•The plasma pressure exists in the stochastic region.

In collisional plasmas($\lambda_e < L_k < L_c$), radial heat diffusivity is defined by,

$$\chi_r = D_{FL} \chi_{\parallel} / L_k$$

This formula means parallel diffusion is effective as well as perpendicular diffusion.

3.3D MHD Equilibrium studies

3.2 3D MHD Equilibrium with magnetic island

Magnetic shear control experiments

Resonant magnetic field



- LHD has the compensation coil system to cancel out the error field and to perform advanced divertor scenario (LID)
- Dominant Fourier component is m/n = 1/1.
- Negative coil current can cancel out the natural error field with m/n = 1/1.



Natural island : $f = -90^{\circ} \sim -126^{\circ}$





Intrinsic islands



- LHD has the compensation coil system to cancel out the error field and to perform advanced divertor scenario (LID)
- Dominant Fourier component is m/n = 1/1.
- Negative coil current can cancel out the natural error field with m/n = 1/1.



Natural island : $f = -90^{\circ} \sim -126^{\circ}$



Magnetic shear is controlled by NBCD





The magnetic shear can be scanned in the wide rage by switching the direction of NBI during the discharge.



Flattening of Te with weak magnetic shear at rational surface of iota =0.5



The flattening of electron temperature profile is observed in the discharge with the switch of NBI from of co- to counter, where the magnetic shear becomes weak.

Magnetic structure near the rational surface





Flattening of Te \leftarrow stochastization but NOT Flattening of Te \rightarrow stochastization Heat flux parallel to magnetic field is much larger than Heat flux perpendicular to magnetic field.

The stochastization can be identified by the cold and heat pulse propagation experiment. Fast pulse propagation is the evidence of stochastization of magnetic flux surface. 2010/6/4 36

Heat pulse propagation

1.0

0.8

0.6

0.4

0.2

0.0

0.1

iota

t=6.8s

t=3.5s

0.2

iota

increase

0.3

r (m)

iota

0.4

co-NBI --> ctr-NBI

The direction of NBI is switched from co- to counterduring the discharge

Edge iota decreases and central iota increases, which results in weaken the magnetic shear.

Heat pulse propagation has been studied with modulation electron cyclotron heating

Flattening of electron temperature and modulation amplitude is observed Modulation amplitude on-axis decreases Modulation amplitude off-axis increases

Heat pulse propagates very quickly towards the plasma edge.





Bifurcation phenomena of magnetic island







There is no MHD instability observed at the onset of temperature flattening.

The temperature fluctuations in the frequency range of 0.8 - 1.2kH appears afterwards with a partial temperature flattening

Relation of island width to magnetic shear



Island healing → island stochastization: no interchange mode stochastization → nesting island → healing interchange mode is excited

Clear hysteresis is observed In the relation between island width and magnetic shear



K.Ida et al., Phys. Rev. Lett, 100 (2008) 045003

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4.3D MHD instability studies

4.1 Magnetic shear control experiments

Configurations for Magnetic Shear Effect



 γ_c (= 5 a_c/R_0) was controlled at fixed R_{ax} (3.6 m) for changing the magnetic shear on i = 1 resonance

- Reduction of γ_c decreases the magnetic shear and V'' on the resonance
- Optimal γ_c for high- β was 1.20 because of high heating efficiency due to reduction of Shafranov shift



Characteristics of *m*/*n* = 1/1 mode





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Occurrence of Non-Rotating Mode

• Large m/n = 1/1 mode without rotation appeared in $\gamma_c = 1.13$ configuration

1.5

1.0

0.5

0 20 10

40 30 20

10

10

107

Time (sec)

0.836

- ideal unstable regime $(D_1 > 0)$
- The mode caused $T_{\rm e}$ profile-flattening around the resonance
- Plasma current decreasing magnetic shear enhances the mode activity further.

0.2

2.0

T_(keV)

 \Rightarrow magnetic shear effect





S.Sakakibara, FS&T 2006

Shot#55397



Shot#55397

t = 0.803 s

1.5

1.5

Radial Magnetic Flux Measurements



24 saddle loops (2 arrays) have been installed inside vacuum vessel for measuring magnetic flux due to equilibrium currents and locked mode.





Shot#55397, R_{ax} = 3.6 m, B_{t} = -1 T, γ = 1.13

n (10¹⁹ m⁻³)

Appearance of the Mode

Minor collapse occurs at 0.82 s

► Then toroidal periodicity of flux profile is suddenly broken.



2

1

Technique of Flux Analysis



► Comparison between measured $DF_r = F_{r1} - F_{r2}$ and $DF_{1/1}$ calculated by multi-filament method

► b_r component on the resonance $b_r = m_0/4p^*I_s/r_s$ and spatial position of the mode can be estimated

Boozer Coordinates (VMEC)

$$R(r) = \sum R_{mn} \cos(mq_{B} - nf_{B})$$

 $Z(r) = \sum Z_{mn} \sin(mq_{B} - nf_{B})$
 $f(r) = f_{B} \sum f_{mn} \cos(mq_{B} - nf_{B})$
 $i/2p$
 $= f_{B} \swarrow \vartheta_{B}, m = km', n = kn' (k: degree)$
 $N_{fil}m' (f direction), N_{fil} \swarrow m' (q direction)$
fil.current : $I = I_{s} \cos(mq_{B} - nf_{B} + a)$
 $I_{s} = N_{fil}mI_{fil}$

Estimated b_r is likely to be produced by ...

- difference of PS profiles

- instability



$\gamma_{\rm c}$ and I_p Dependences of the mode





• The mode appears even in high- γ_c if I_p exceeds a threshold. • A threshold of the plasma current decreases with decreasing γ_c

• Operation limit is qualitatively consistent with ideal theory



and I_n

Plasma rebounded against "Limit"

- Even if $\gamma_{\rm c}$ is sufficiently high, the $I_{\rm p}$ causes the minor collapse
- Plasma is rebounded from "limit" three times.







Counter Ip experiment

- Magnetic shear is essential for excitation of the mode?
- \Rightarrow counter- I_p experiments (Nov.2,2005)
- Sawtooth-like Oscillation was observed, and the inversion radius identified by FIR signals is located around $\iota/2p = 1$
- $\Phi_{\rm r}$ signals also indicate that the *n* number is odd







 $R_{ii} = 3.6 \text{ m}, B_i = 0.75 \text{T}, \gamma = 1.13 \text{ Shot#59058}, 59063$

Verification of I_p effect on 1/1 mode



- Plasma exists near "onset" region of the m/n=1/1 mode.
- Toroidal location of the mode does not depend on the direction of B_{t} .



<β_{dia}> (%)

Specification of PC Power Supply



Capacity of PC PS was increased

- IS, IV coils : < 6. 2 kA
- H 45 V, P 213 V (SS H 45 V, P 33 V)
- Operation with \leq 1.5 T is available
- Fixed B_t or Fixed I_{HC} operations





6.6kV



Example of R_{ax} Swing Discharge (2.0 sec)



R_{ax} Swing

Reference ·

Reference

 $R_{ax} = 3.6 \text{ m}, B_t = -0.425 \text{ T}, \gamma_c = 1.20$

NBI#1,3 (Co.,1.3 s~) NBI#2 (Ctr., 1.8s~)

R_{ax} Swing

0.5

0.4

0.3

0.2

0.1

 $R_{ax} = 3.6 \text{ m} \rightarrow 3.5 \text{ m}$ for 2 sec

Both R_{ax} and R₀₀ shifts with the preset



3.9

3.8

3.7

3.6

R_{ax} (m)

Characteristics of m/n = 1/1 mode



Several differences of characteristics of the mode between "*non-rotating*" and "*rotating*" modes:

	"non-rotating" mode (low- γ_c , large I_p)	" <i>rotating</i> " mode (Standard, high-β)
radial location	$\rho \sim 0.7$ (currentless)	$\rho \sim 0.9$
configuration	weak shear, magnetic hill	magnetic hill
observation	$D_{\rm I} > 0, D_{\rm R} > 0$	$D_{\rm I} < 0, D_{\rm R} > 0$
frequency	DC ~ several Hz	several kHz
spatial location		rotating
S dependence	Not clear	strong



Interaction of the modes with Resonant magnetic field

4.3D MHD instability studies

4.2 Interaction with magnetic islands

LHP MIRS

Interaction with "Rotating" Mode

- Finite pressure gradient /near i = 1 surface exists till $I_{LID} \le 220$ A/T, whereas it gradually decreases with I_{LID} .
- Amplitude of the mode decreases with reduction of the gradient, and the mode disappears despite finite gradient still remains.

Then the mode frequency slowed down





Interaction with "Non-Rotating" Mode



 The mode could be completely suppressed by giving optimal island width, and $<\beta>$ recovered.

- The location and saturation-level of the mode strongly depended on that of given static island.
- Non-linear instability like locked mode?





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 $\theta_{11-0} = -93 \text{ (deg)}$

= -82 (deg).

= 1 (deg)

 θ_{11-0} = 55 (deg)

4.0

4.5

 $\boldsymbol{\theta}_{_{11-r}}$

4.3D MHD instability studies

4.3 Core Density Collapse

Core Density Collapse



Observed in SDC plasma
Decreased Density
Unchanged temperature
Observed fluctuation in the peripheral region



Finite- β equilibrium in a SDC Plasma





Numerical model



$$\frac{\partial \rho}{\partial t} = -\nabla \cdot (\rho \mathbf{v}) \qquad (1)$$

$$\rho \frac{\partial}{\partial t} \mathbf{v} = -\rho \omega \times \mathbf{v} - \rho \nabla (\frac{v^2}{2}) - \nabla p + \mathbf{j} \times \mathbf{B}$$

$$+ \frac{4}{3} \nabla [v \rho (\nabla \cdot \mathbf{v})] - \nabla \times [v \rho \omega] \qquad (2)$$

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E} \qquad (3)$$

$$\frac{\partial p}{\partial t} = -\nabla \cdot (p \mathbf{v}) - (\gamma - 1) p \nabla \cdot \mathbf{v}$$

$$+ (\gamma - 1) [v \rho \omega^2 + \frac{4}{3} v \rho (\nabla \cdot \mathbf{v})^2 + \eta \mathbf{j} \cdot (\mathbf{j} - \mathbf{j}_{eq})] \qquad (4)$$

$$\mathbf{E} = -\mathbf{v} \times \mathbf{B} + \eta (\mathbf{j} - \mathbf{j}_{eq}) \qquad (5)$$

$$\mathbf{j} = \frac{1}{\mu_0} \nabla \times \mathbf{B} \qquad (6)$$

$$\omega = \nabla \times \mathbf{v} \qquad (7)$$

•4th order finite difference
•4th order Runge-Kutta method for time integration
•Grid points on the cylindrical coordinates (R,φ,Z)

Simulation results



•Saturated for $400\tau_{A.}$ •After $300\tau_{A}$, P_{max} decreases quickly. Central pressure decreases.Edge pressure increases

Simulation results



Perturbation in linear phase



.5 (a)



5. Application of 3D tools to Tokamaks

Applications to ITER

Plasma response to TBM ripple and coupling Ferrite insert are urgent issues.





Summary

- •The sterallator is a platform to explorer 3D physics.
- •3D MHD equilibrium response is studied in stellarator.
- •The stochastization is naturally caused by 3D configuration. => 3D equilibrium responses
- •Coupling MHD instability and 3D magnetic field are discussed.
- •MHD modeling of CDC event is discussed.
- •Applications of 3D tools to tokamaks are shown.